

Team A2: UltraLight Final Presentation

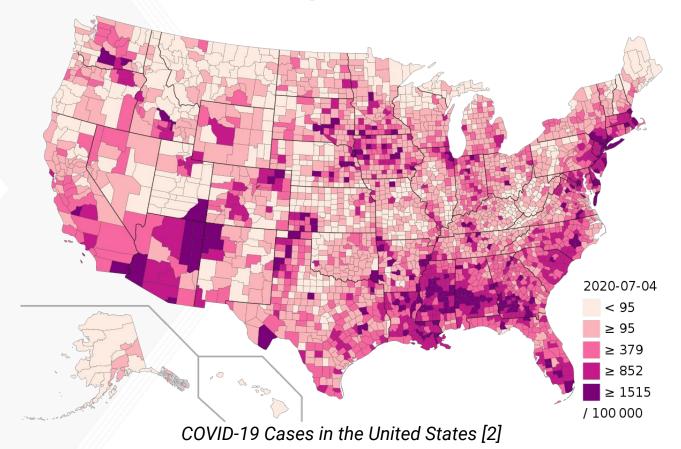
July 21st, 2020

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Background



Problem Background



~4,000,000 confirmed cases

~140,000 thousand confirmed deaths [1]



Problem Background

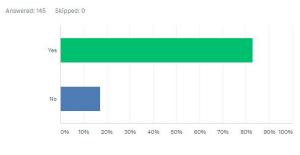
- Shopping carts have been shown to have a higher bacteria count per square foot than bathroom surfaces, and may even be home to fecal matter. [3] [4]
- In addition to these bacterial threats, current pandemic concerns are changing the shopping experience. [5]

On a scale of 1 to 100, with 1 being dirty and 100 being clean, how clean do you think shopping carts and baskets are?





If a grocery store can implement a system to sanitize shopping carts, would you shop there more often than stores that don't?



ANSWER CHOICES	RESPONSES	
Yes	82.76%	120
No	17.24%	25
TOTAL		



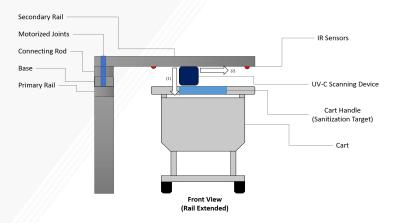
Problem & Customer Needs Statement

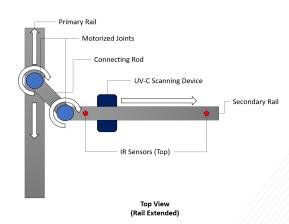
- A way to eliminate bacteria and viruses on commonly contacted surfaces becomes critical to ensuring the welfare of shoppers and employees, and operational capacity of stores. [6]
- To ensure the health of their businesses, retail and grocery stores must be able to ensure the health of their customers (the most loyal of whom are often the most vulnerable), inspire confidence in their ability to continue operation in a post COVID-19 world, and do their part to prevent possible future pandemics. [7] [8]
- GOAL: Reduce pathogen spread within grocery stores by focusing on the disinfection of one of the most commonly contacted surfaces



Solution: UltraLight Sanitizing System

- UV-C ultraviolet germicidal light for sanitizing cart handles
- System placed in cart return to sanitize stored carts
- Linear actuator system for translation to carts
- Rotational component to allow for deviations in cart orientation
- Ultrasonic sensors for detection of cart handle
- 99.9% disinfection rate in 35 seconds



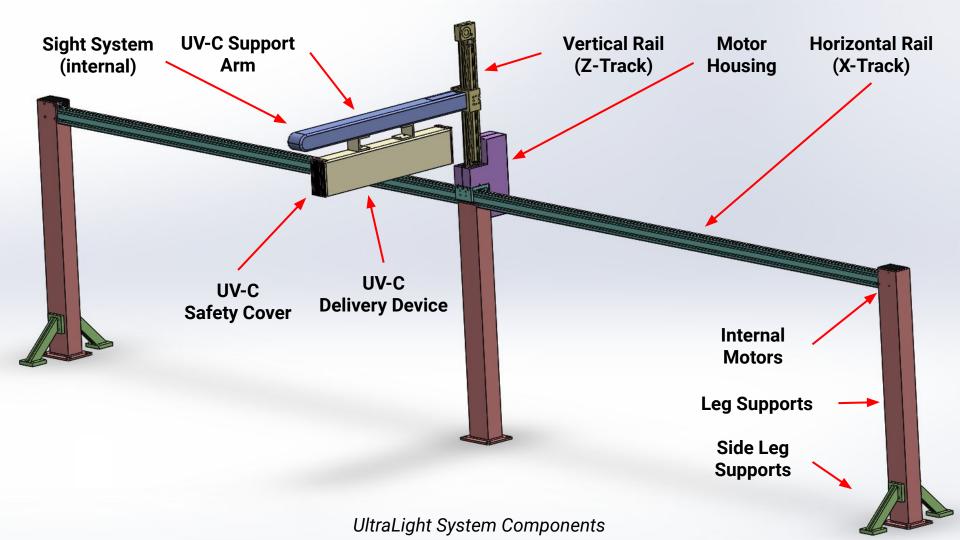




Solution

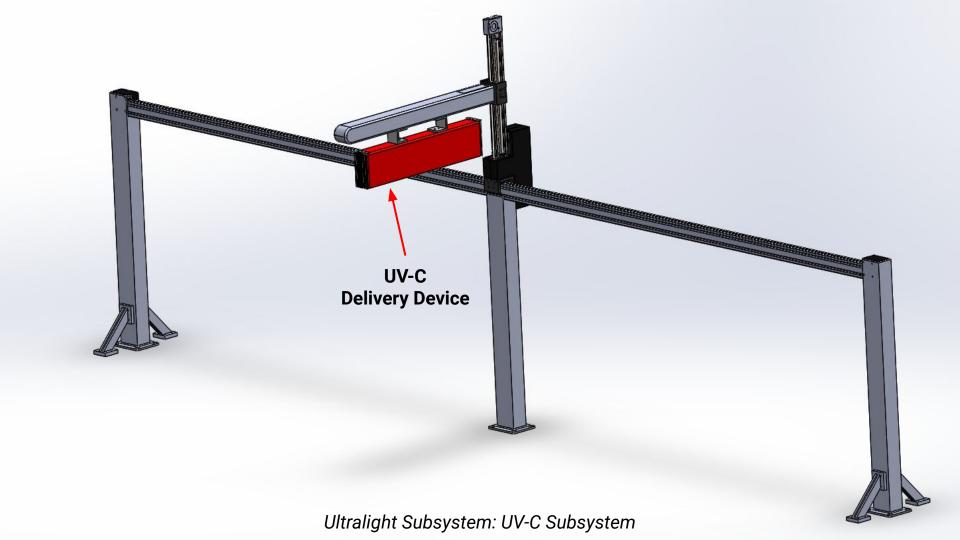






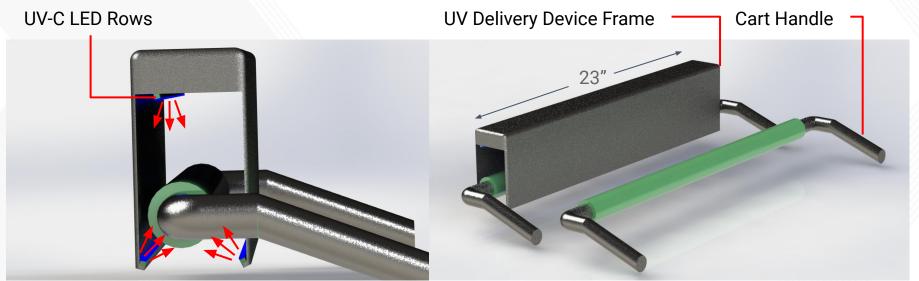
UV-C Subsystem





UV-C Subsystem

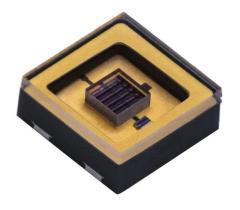
- "Heart" of the system
- UV-C Delivery Device delivers ultraviolet light to the entire circumference of cart handle
- Positioning ensures full surface area application without line of sight from below
- Geometrically optimized operation for various carts (Walmart, Kroger, Publix, and Sprouts)



UV-C LED Design Choice

- LED bulbs are more expensive per unit of delivered power than fluorescent bulbs, but have multiple beneficial properties
 - Higher Efficiency
 - Long Lifetime
 - Small Geometry
 - No Warm-Up Time
 - No Cyclical Usage Degradation

Benefit: Smaller, More Powerful Lights



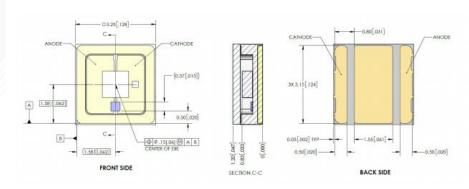
UV-C LED Illustration



UV-C LED Design Choice

- LED Choice: Luminous XBT-3535-UV Surface Mount UVC LED [9]
 - Broke price barrier at \$0.10/mW, for lowest cost on market [10]
 - UV-C power: 80 mW
 - Size: 3.5 mm x 3.5 mm x 1.2 mm
 - Viewing Angle: 130°

Mechanical Dimensions





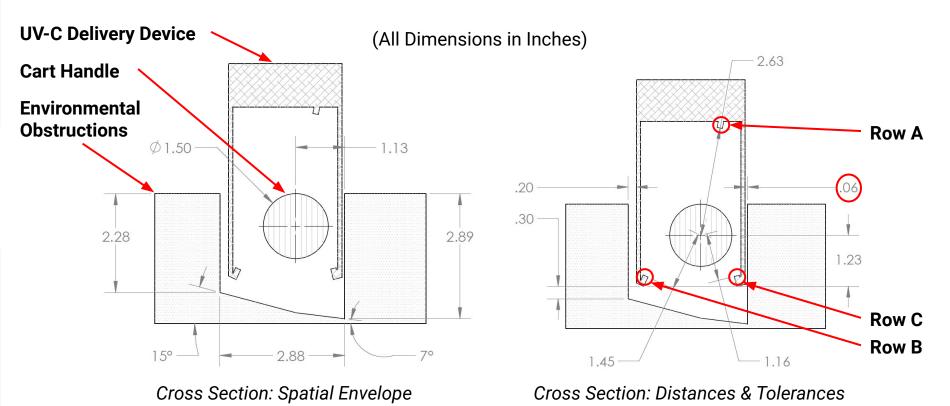
UV-C Delivery Device

- Design Parameters:
 - Triangular configuration for least number of rows of LEDs to deliver UV-C light to the entire circumference of the cart handle
 - Fits within gap provided, with clearance of ±0.06 inches both vertically and horizontally to account for the linear actuator resolution
 - Bottom light rows oriented so that 130° view factor is contributing only to the cart handle, and not visible from ground

 Optimized using SOLIDWORKS geometric constraints to achieve fully defined parameters

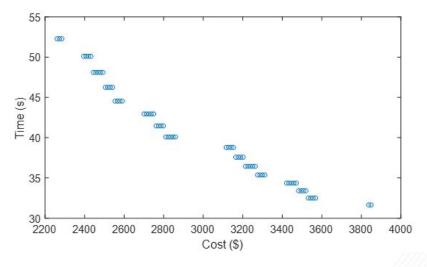


UV-C Delivery Device



LED Optimization

- Developed an algorithm to optimize disinfection time to deliver irradiance using the Inverse Square Law
 - 35 s @ \$3,837.08
 - 95 mJ/cm² for 99.9% disinfection rate [11]
 - Allowable handle diameters: 0.75" to 1.5"
 - Allowing for rate of 10% degradation in LED power output



Disinfection Time per Handle vs. Cost of UV-C LEDs

Total LEDS: 314

o Row A: 164 LEDs

o Row B: 90 LEDs

o Row C: 60 LEDs



LED Optimization

Assumptions:

- Inverse Square Law valid for light source (distance dependent)
- Maximum number of LEDs on furthest row for minimum time

• Calculations:

- Calculated time for LED row at maximum distance to achieve 95 mJ/cm² on the cart handle surface
- Calculated equivalent power (number of evenly spaced LEDs) to achieve the same time value for other rows, at varying distances

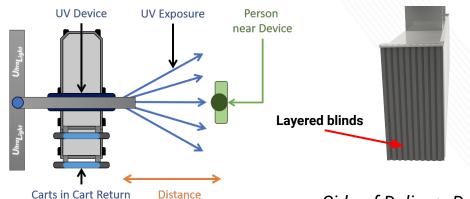
Considerations:

- Allowed for maximum distance of 1.5" inches, minimum distance of 0.75", to account for range of diameters needed
- Allowed for degradation of power output, subject to change across the lifetime of the bulb



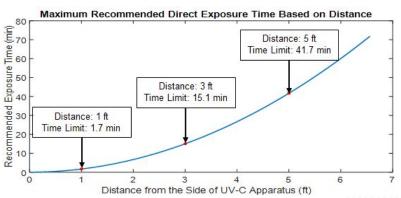
UV-C Safety

- Referenced CDC and ASHRAE guidelines on safe UV-C exposure [12]
- Designed safety cover for sides of UV-C delivery device to limit exposure
- Experimental data required to gage safety cover effectiveness
- Evaluated exposure times from Row B and C for "worst-case" scenario, without safety cover



Visual Representation of Exposure

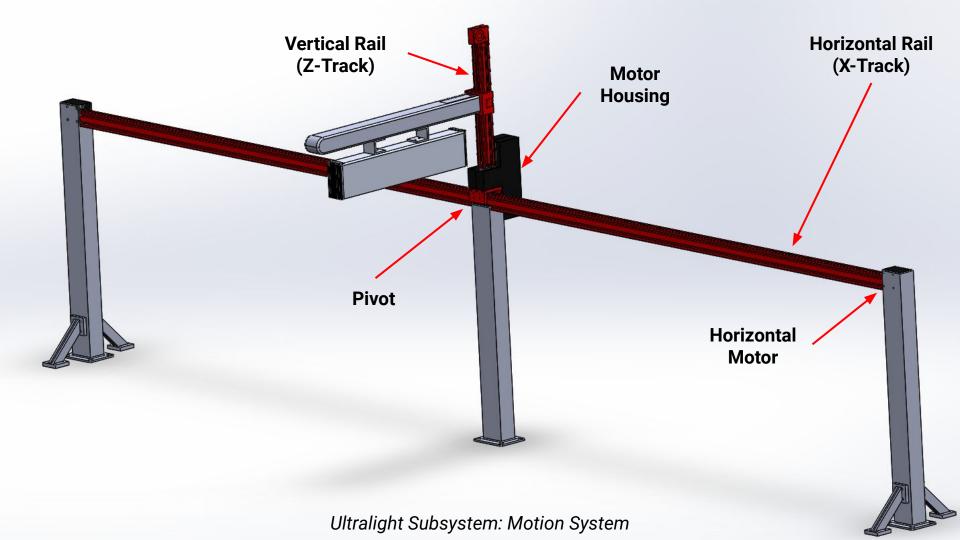
Side of Delivery Device with Safety Cover



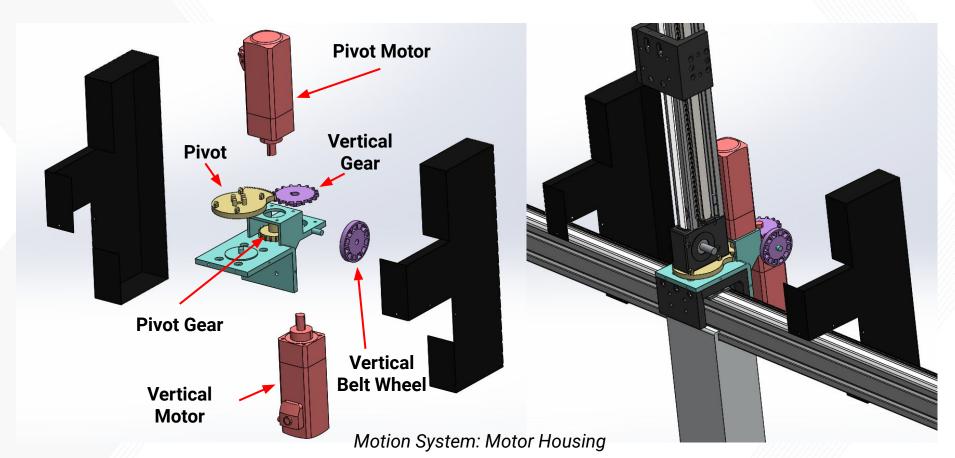
"Worst-Case" Direct Exposure Limits



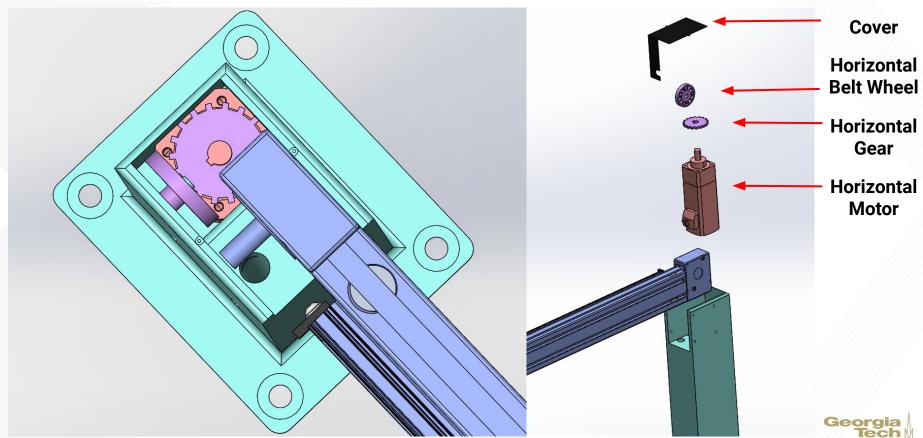




Motor Housing



Horizontal Motor



Motion System: Horizontal Motors

- "Muscles" of the system
- Allow the UV-C delivery device to move to the cart handles
- Motors drive the vertical and horizontal rails to position the UV-C device
- Pivot allows the UV-C device to rotate and accurately orient itself over cart handle before dropping



Oriental Motor ARM46AC-PS25
[13]



Macron Dynamics Inc.: MSA-R15 Actuator [14]



Oriental Motor ARM66AC-N25

[15]

- Macron Dynamics MSA-R15
 Actuator chosen for both
 vertical and horizontal rails.
- Resolution of 0.4 mm/m
- Customizable rail lengths to account for variations



Macron Dynamics Inc.: MSA-R15 Actuator

Specifications

Motion	Horizontal or Vertica
Max Speed – horizontal [vertical] – mm/sec	5000 [5000]
Max Load – horizontal [vertical] – lbs.	50 [25]
Repeatability - mm	+/- 0.025
Moment Load Max – inlbs. [Nm]	310 [35]
Positional Accuracy – mm/meter	+/- 0.4
Acceleration max – G's	20
Ultimate tensile strength of belt - lbs. [N]	800 [3559]
Recommended belt running load – lbs. [N]	200 [889]
Cart Guide	Linear bearing with profile rail

[14]



Horizontal Rail and Pivot ARM46AC-PS25, 1.65 in. Closed Loop Stepper Motor

- Required torque of 1.5 Nm
- Resolution: 0.0144 °/Pulse
- Stop Position Accuracy: ±4 arc minutes (±0.067°)



Oriental Motor ARM46AC-PS25



Vertical Rail ARM66AC-N25, 2.36 in. Closed Loop Stepper Motor

- Required torque of 6.57 Nm
- **Resolution**: 0.0144 °/Pulse
- Stop Position Accuracy: ±4 arc minutes (±0.067°)

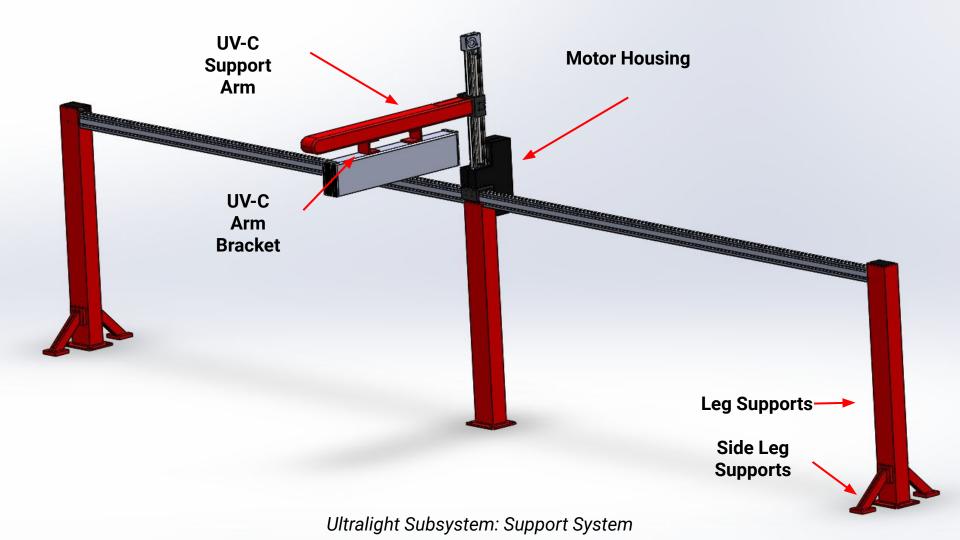


Oriental Motor ARM66AC-N25



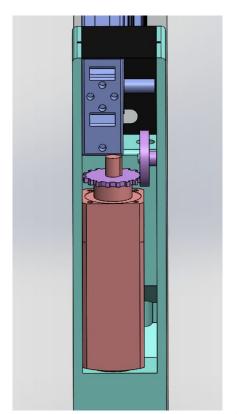
Support System





Support System

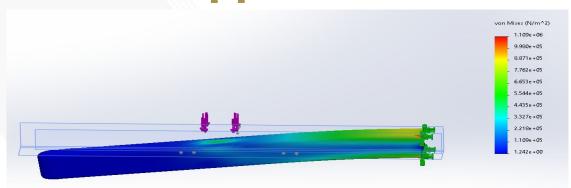
- "Skeleton" of the system
- Support and house the motion system and enables stability of the structure
- Custom designed to achieve specific support goals
- Designed iteratively to ensure appropriate support
 - Can a 250 lb person lean on the rails?



Support System: Support Leg Cross Section

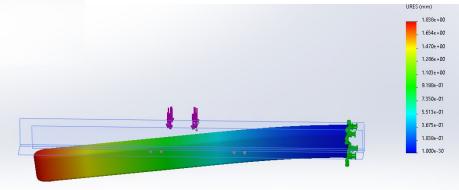


FEA- Support Arm



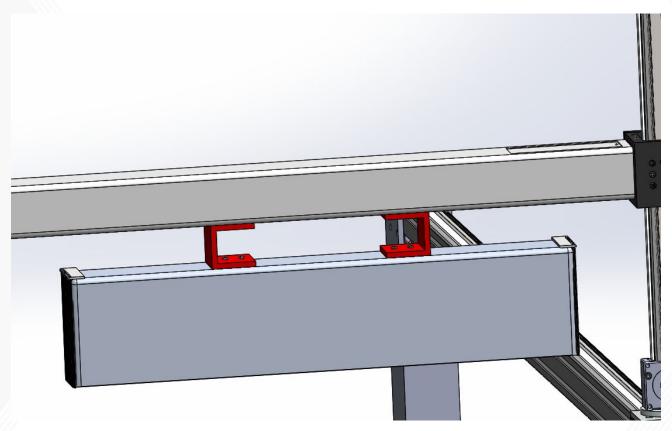
UV-C Support Arm: Stress Analysis

Elongation at Break	10 - 50 %
Elongation at Yield	1.7 - 6 %
Flexibility (Flexural Modulus)	1.6 - 2.4 GPa
Hardness Shore D	100
Stiffness (Flexural Modulus)	1.6 - 2.4 GPa
Strength at Break (Tensile)	29.8 - 43 MPa
Strength at Yield (Tensile)	29.6 - 48 MPa
Toughness (Notched Izod Impact at Room Temperature)	200 - 215 J/m
Toughness at Low Temperature (Notched Izod Impact at Low Temperature)	20 - 160 J/m
Young Modulus	1.79 - 3.2 GPa



UV-C Support Arm: Amplitude Analysis

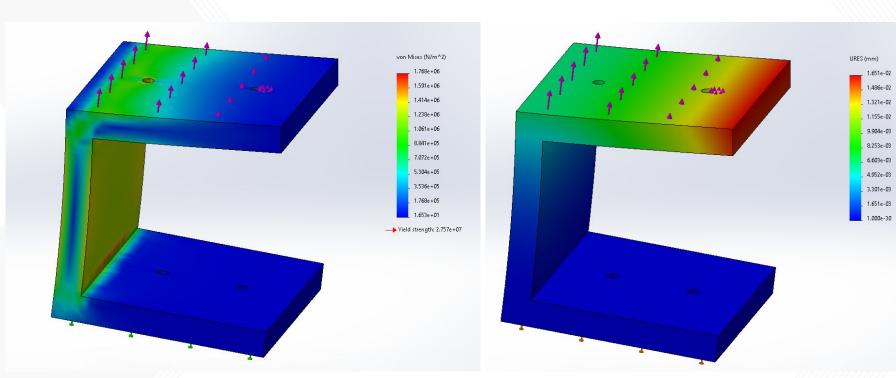
FEA- UV Bracket





Support System: UV Brackets

FEA - UV Bracket



UV-C Bracket: Stress Analysis

UV-C Bracket: Amplitude Analysis

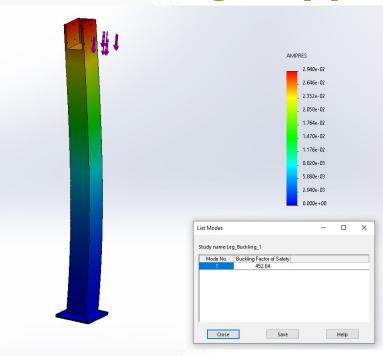


FEA - Leg Support

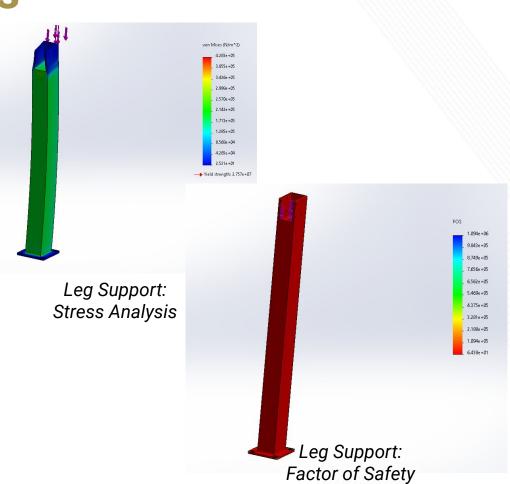




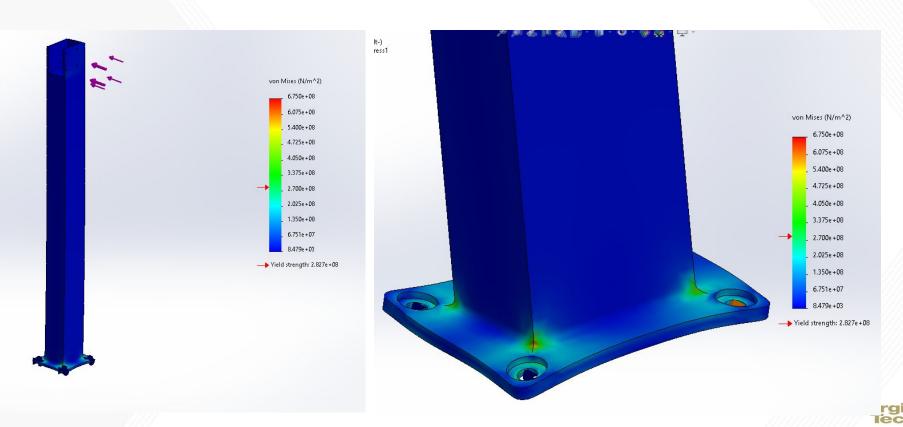
FEA - Leg Supports



Leg Support: Buckling Force

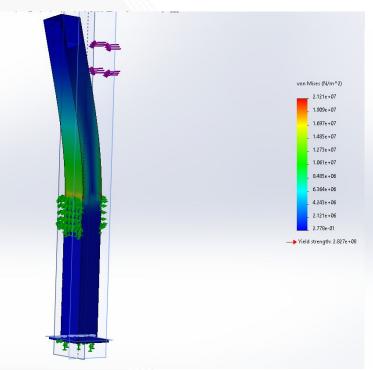


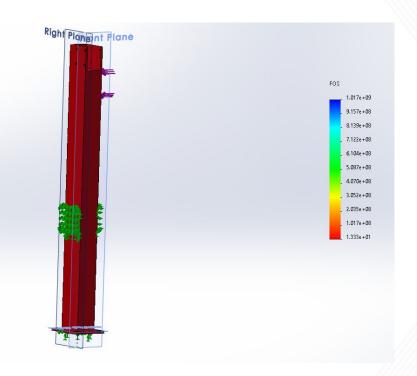
FEA- Leg Tipping Force



CREATING THE NEXT

FEA- Leg Tipping with Side Leg Supports





Leg Support with Side Leg Support: Tipping Force Analysis

Leg Support with Side Leg Support: Factor of Safety Analysis

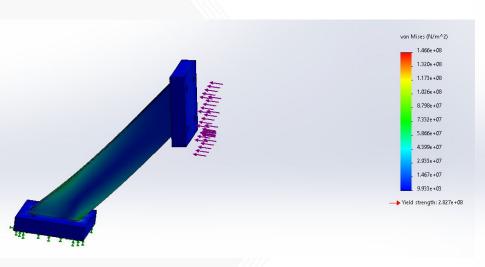


FEA - Side Leg Support

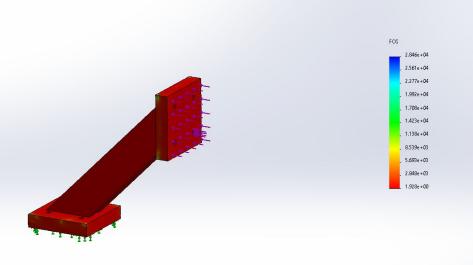




FEA - Side Leg Support



Side Leg Support: Stress Analysis



Side Leg Support: Factor of Safety



Chosen Fasteners

All required safety factors: 1.3-1.5

- Securing to Ground: Stainless steel 316, 1/4" diameter bolts
 - Required shear strength 1590 lb
 - Chosen bolt provides safety factor of 3.11
- Securing Legs to Rails: Grade-8 Steel with Coarse Threads 1¼" diameter, plated
 - Required withstandable torque 1101.02 ft-lbs
 - Safety factor of 1.86
- Securing Support Arm: Grade-8 Steel, ½" diameter, 9 threads/inch
 - Required withstandable torque 388.404 ft-lbs
 - Safety factor of 1.55 allowing for lubrication



Sight System



Sight Sensor

- Ultrasonic sensors use sound for detection, and therefore are not prone to detection issues stemming from [16]:
 - Colors
 - Reflectivity
 - Transparency
 - Wet Surface
 - Dirty Surface
- Model a cost effective solution for ≤1mm resolution



Baumer U500.PAO.2-GP1J.72F Sensor [17]



Materials & Manufacturing



		1			
Component	Number	Vendor	Model/Material	Manufacturing Method	Selection Justification
UV-C Delivery Device Frame	1	N/A	Aluminum Alloy 1060	Casting	Low density, high melting point
UV-C LEDs	314	Luminus	XBT-3535-UV Surface Mount UVC LED	N/A	Best price per power at \$0.10/mW
UV-C Support Arm	1	N/A	ABS Plastic	3D Printing	Low weight, low cost for strength
UV-C Side Safety Cover	1	N/A	Rubber Silicone	3D Printing	Flexible, resistant to UV-C
Motion System Leg Supports	1	N/A	Carbon Steel	Casting	Meets strength requirements, more cost effective than stainless steel
Motion System "X-track"	1	Macron Dynamics, Inc.	MSA-628 Actuator	N/A	Resolution of ± 0.4 mm/m of travel
Motion System "Z-track"	1	Macron Dynamics, Inc.	MSA-628 Actuator	N/A	Resolution of ± 0.4 mm/m of travel
Motion System Horizontal & Pivot Motors	3	Oriental Motor	ARM46AC-PS25, 1.65" Closed Loop Stepper Motor	N/A	Capable of achieving required torque of 1.5 Nm, 0.0144°/pulse
Motion System Vertical Motor	1	Oriental Motor	ARM66AC-N25, 2.36 in. Closed Loop Stepper Motor	N/A	Capable of achieving required torque of 1.5 Nm, 0.0144°/pulse
Sight System Ultrasonic Sensor	2	Baumer	U500.PAO.2-GP1J.72F	N/A	Best price for range and ≤1mm resolution
1////		1	I		

System in Action





Safety, Cost, & Impact



Safety, Risk & Liabilities

- Ultraviolet Light warnings to avoid direct exposure
 - Warning labels required
- Structural stability
 - Warning labels required
- Wiring
 - Routing, spooling, resolving entanglement issues, trip hazard
- Force sensors
 - Force transducers for interference detection
 - Emergency stop
- System operation warnings
 - Warning regarding process start
 - Indicator when operating
- Misuse, Mishandling
 - Keycode or other preventative measure so only employees may access
 - Indicator to show which carts are clean





Cost Analysis

Disinfectant Wipes

(Assumptions: 14 hours a day, \$7.25/hr labor, \$0.71/hr material)

Daily Cost: \$111.44/day

UltraLight System

(Assumption: \$0.09/kWh)

Initial Cost of System: \$28,284

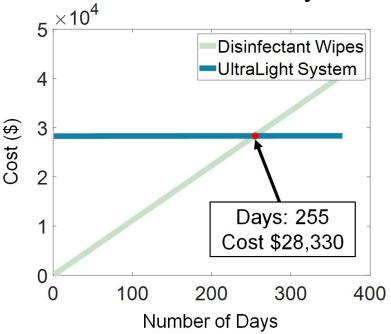
Daily Cost: \$0.19/day

Break-even Point: 9 months

Yearly Savings: \$40,606/year

(Yearly Savings after break-even point)







Impact

Societal Impact

- Reduced pathogen spread with implementation
- Pre-existing insurance for future pandemics
- More affordable, accurate than pre-existing disinfection methods
- Higher customer confidence with minimum changes to experience

Environmental Impact

- Unlike other types of UV, UV-C does not produce ozone
- Low risk of UV exposure for human contact

Sustainability Impact

- Low energy, especially compared to other UV-C disinfection devices
- Zero-waste, unlike gloves, or disinfection wipes, or sanitizer fluids

Future Work

"Nervous" system

- Wiring (outsource the electrical system to an electrical engineer)
- Central control ("brain" to control systems)
- Start/stop controls, emergency stop functions

"Signals" system

- Visual indicators to demonstrate when carts are clean or dirty
- Emergency sensors (force transducers)

Experimental validation

- UV-C safety covers
- Disinfection rates
- Physical prototypes



UltraLight

99.9% Disinfection Rate in 35 Seconds





Questions?



References

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